

## August 1996

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## NM93C46A 1,024-Bit Serial Interface, Standard Voltage CMOS **EEPROM (MICROWIRE™ Synchronous Bus)**

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## **General Description**

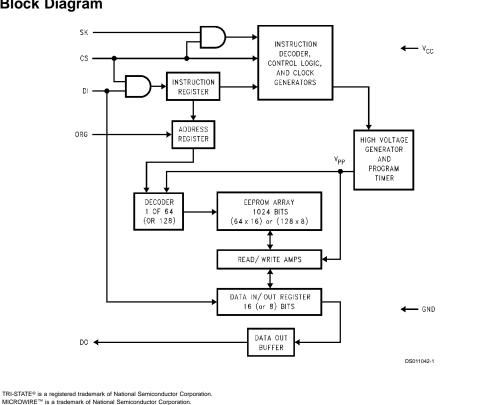
The NM93C46A is 1,024 bits of CMOS nonvolatile, electrically erasable memory available as either 64 16-bit registers or 128 8-bit registers. The user organization is determined by the status of the ORG input. The memory device is fabricated using National Semiconductor's floating gate CMOS process for high reliability, high endurance, and low power consumption. The NM93C46A is available in both 8-pin SO and TSSOP packages for space considerations.

The EEPROM is MICROWIRE compatible for simple interfacing to a wide variety of microcontrollers and microprocessors. There are 7 instructions that operate the NM93C46A: Read, Erase/Write Enable, Erase, Write, Erase/Write Disable, Write All, and Erase All.

The NM93C46A defaults to the 64 x 16 configuration if the ORG pin (Pin 6) is left floating, as it is internally pulled up to V<sub>cc</sub>.

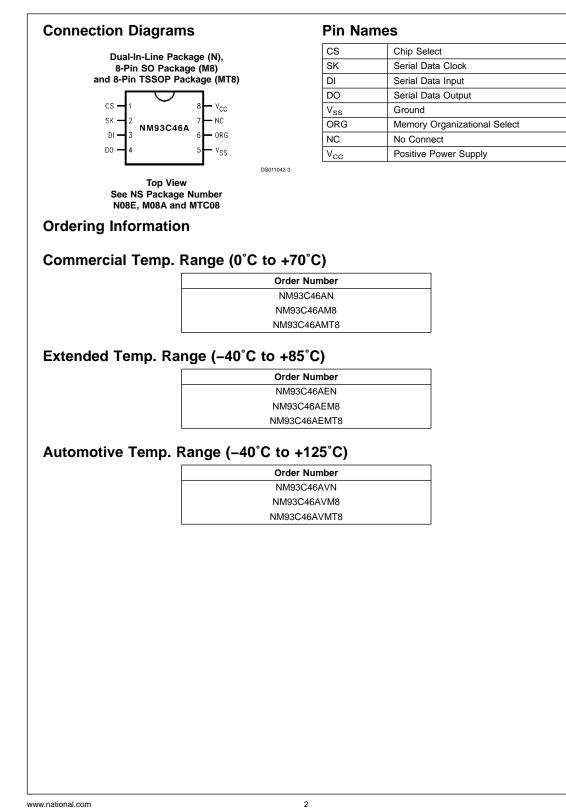
### Features

- 4.5V to 5.5V operation in all modes
- Typical active current of 200 µA; typical standby current of 10 µA
- Self-timed programming cycle
- Device status indication during programming mode
- No erase required before write
- Reliable CMOS floating gate technology
- MICROWIRE compatible serial I/O
- 40 years data retention
- Endurance: 10<sup>6</sup> data changes
- Packages available: 8-pin TSSOP, 8-pin SO, 8-pin DIP



NM93C46A 1,024-Bit Serial Interface, Standard Voltage CMOS EEPROM (MICROWIRE Synchronous Bus)

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## Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Ambient Storage Temperature	-65°C to +150°C
All Input or Output Voltages:	
with Respect to Ground	V <sub>CC</sub> + 1 to -0.3V
Lead Temperature	
(Soldering, 10 Seconds)	+300°C

## **DC and AC Electrical Characteristics**

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Symbol	Parameter	Part Number	Conditions	Min	Max	Units
I <sub>CCA</sub>	Operating Current	NM93C46A	CS = V <sub>IH</sub> , SK = 1 MHz		1	mA
		NM93C46AE/V	SK = 1 MHz			
I <sub>ccs</sub>	Standby Current		CS = 0V, ORG = $V_{CC}$ or NC		50	μA
I <sub>IL</sub>	Input Leakage		$V_{IN} = 0V$ to $V_{CC}$ (Note 2)	-1	1	μA
I <sub>ILO</sub>	Input Leakage		ORG tied to V <sub>CC</sub>	-1	1	μA
	ORG Pin		ORG tied to $V_{SS}$ (Note 3)	-2.5	2.5	
I <sub>OL</sub>	Output Leakage		$V_{IN} = 0V$ to $V_{CC}$	-1	1	μΑ
V <sub>IL</sub>	Input Low Voltage			-0.1	0.8	V
V <sub>IH</sub>	Input High Voltage			2	V <sub>cc</sub> + 1	V
V <sub>OL1</sub>	Output Low Voltage		I <sub>OL</sub> = 2.1 mA		0.4	V
V <sub>OH1</sub>	Output High Voltage		I <sub>OH</sub> = -400 μA	2.4		V
V <sub>OL2</sub>	Output Low Voltage		I <sub>OL</sub> = 10 μA		0.2	V
V <sub>OH2</sub>	Output High Voltage		I <sub>OL</sub> = -10 μA	V <sub>CC</sub> - 0.2		V
f <sub>sк</sub>	SK Clock Frequency	NM93C46A	(Note 4)	0	1	MHz
		NM93C46AE/V		0	1	
t <sub>sĸн</sub>	SK High Time	NM93C46A		250		ns
		NM93C46AE/V		300		
t <sub>SKL</sub>	SK Low Time			250		ns
t <sub>cs</sub>	Minimum CS	NM93C46A	(Note 5)	250		ns
	Low Time	NM93C46AE/V		250		
t <sub>css</sub>	CS Setup Time	NM93C46A		50		ns
		NM93C46AE/V		50		
t <sub>DH</sub>	DO Hold Time			70		ns
t <sub>DIS</sub>	DI Setup Time	NM93C46A		100		ns
		NM93C46AE/V		200		
t <sub>CSH</sub>	CS Hold Time			0		ns
t <sub>DIH</sub>	DI Hold Time			20		ns
t <sub>PD1</sub>	Output Delay to "1"	NM93C46A			500	ns
		NM93C46AE/V			500	
t <sub>PD0</sub>	Output Delay to "0"	NM93C46A			500	ns
		NM93C46AE/V			500	
t <sub>SV</sub>	CS to Status Valid	NM93C46A			500	ns
		NM93C46AE/V			500	
t <sub>DF</sub>	CS to DO in	NM93C46A	CS = V <sub>IL</sub>		100	ns
	TRI-STATE®	NM93C46AE/V			100	
t <sub>WP</sub>	Write Cycle Time				10	ms

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## EDS Rating

NM93C46A

NM93C46AE

NM93C46AV

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## **Operating Range**

Ambient Operating Temperature 0°C to +70°C -40°C to +85°C -40°C to +125°C Power Supply (V<sub>CC</sub>)

2000V

4.5V to 5.5V

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## Capacitance

 $T_A = +25^{\circ}C, f = 1 \text{ MHz}$ 

Symbol	Test	Max	Units
C <sub>OUT</sub>	Output Capacitance	5	pF
C <sub>IN</sub>	Input Capacitance	5	pF

## **AC Test Conditions**

Output Load	1 TTL Gate and $C_L = 100 \text{ pF}$
Input Pulse Levels	0.4V and 2.4V
Timing Measurements Reference Level	
Input	1V and 2V
Output	0.8v and 2.0V

Note 1: Stress ratings above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and operation of the device at these or any other conditions above those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note 2: Typical leakage values are in the 20 nA range.

Note 3: The ORG pin may draw >1 µA when in the x8 mode due to an internal pull-up transistor.

Note 4: The shortest allowable SK clock period =  $1/f_{SK}$  (as shown under the  $f_{SK}$  parameter). Maximum SK clock speed (minimum SK period) is determined by the interaction of several AC parameters stated in the datasheet. Within this SK period, both  $t_{SKH}$  and  $t_{SKL}$  limits must be observed. Therefore, it is not allowable to set  $1/t_{SK} = t_{SKH}$  (minimum) +  $t_{SKL}$  (minimum) for shorter SK cycle time operation.

Note 5: CS (Chip Select) must be brought low (to V<sub>IL</sub>) for an interval of t<sub>CS</sub> in order to reset all internal device registers (device reset) prior to beginning another opcode cycle. (This is shown in the opcode diagrams in the following pages.)

## Interface Pin Description

#### Chip Select (CS):

Chip Select performs several functions. It is used to differentiate between various devices on the same MICROWIRE bus. The rising edge resets the internal circuitry of the device, a function necessary prior to initiating a new cycle. Chip Select (as shown on Block Diagram) also gates the Data Input (DI) and Serial Clock (SK) Input, to disable these functions. In the case of these EEPROMs, Chip Select cannot be tied HIGH even if it is the only device on the bus.

Chip Select must be held HIGH continuously during the course of clocking in the start bit, op-code address, and data-in or data-out. Otherwise the internal circuits will reset and the cycle will have to be started again with a new start bit.

Chip Select initiates the internal programming cycle. The falling edge of Chip Select will start the internal asynchronous programming cycle after a programming op-code has been entered (Erase, Write, Erase All, or Write All). In conjunction with Chip Select, Data-Out (DO) will indicate when programming is complete. If the internal programming is incomplete, then Data-Out pin will be LOW. Then when the internal programming is complete, the Data-Out pin will be HIGH (see Timing Diagrams).

#### Serial Clock (SK):

The Serial Clock input is used to clock all start bits, op-codes, data, addresses, and data bits into or out of the EEPROMs. The clock's rising edge controls the input and output of bits. The falling edge has no effect on the device. The Serial Clock is not necessary for the asynchronous Ready/Busy polling function.

The Serial Clock is in a "Don't Care" at any time Chip Select is LOW. It is also in a "Don't Care" state prior to clocking in a start bit, or during Ready/Busy polling. During either of these last two conditions, Data-In (DI) must be held at a LOW level, otherwise a new start bit will be interpreted.

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## Data-In (DI):

The Data-In pin receives the start bit, address, and input data synchronously. Each bit is clocked in on the rising edge of SK. DI is gated by Chip Select to provide a high degree of noise immunity. Data-In is routed to both the instruction shift register and the data shift register. After the start bit is clocked into the last bit of the instruction register, the clock is switched to the data register to receive input data. To avoid false reading of a start bit, it is safer to keep the Data-In pin at LOW level when not in use.

#### Data-Out (DO):

The Data-Out pin sends Read data onto the MICROWIRE bus and it is clocked out on the rising edge of the Serial Clock. During the Read cycle, the DO output begins to drive actively after the last address bit (A0) is clocked in.

Data-Out also carries the device's status during the asynchronous programming cycle. The Data-Out pin drives LOW while the device is still in its internal programming cycle. After the EEPROM has completed this internal programming, Data-Out will drive HIGH. This is accomplished while Chip Select is held HIGH.

Finally, if Chip Select is pulsed LOW to HIGH, Data-Out pin will again produce a pulse HIGH. Thus indicating the completion of the programming cycle.

To clear the Ready/Busy polling, it is necessary to raise Chip Select and clock in another start bit. Once the start bit is clocked in, Data-Out will return to the HIGH impedance state. It is not necessary to continue with a cycle after this start bit has been clocked in, although it is permissible to start a new cycle with this start bit. This clearing of Ready/ Busy status may be necessary if a bidirectional data bus is used (Data-In tied to Data-Out) as the Data-Out output will interfere with the new data being presented on the Data-In pin. This connecting of the two Data pins is used for three-wire interface schemes.

## Interface Pin Description (Continued)

#### Organization (ORG):

The Organization input (ORG) is available only on the NM93C46A device and it is used to control the internal organization of the memory. The two selectable organizations are 16-bit words and 8-bit words. By connecting the ORG pin to

### Instruction Set for the NM93C46A

 $V_{\rm CC},$  16-bit words are selected. In contrast, by connecting the ORG pin to GND, 8-bit words are selected. If the ORG pin is left floating, then default setting is the 16-bit word. When in the 8-bit mode, one additional address bit is required in the instruction sequence since the depth of the memory is doubled.

The NM93C46A has 7 instructions as described below. Note that the MSB of any instruction is a "1" and is viewed as a start bit in the interface sequence. The next 2 bits carry the op code, the next 6 (or 7) bits carry the address for selection of 1 of 64 16-bit registers or 1 of 128 8-bit registers, depending on memory array organization.

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### 1024 by 16-Bit Organization

(NM93C46A when ORG =  $V_{CC}$  or NC)

Instruction	SB	OP-Code	Address	Data	Comments
		2 Bits	6 Bits	16 Bits	
READ	1	10	A5–A0		Read data stored in selected registers.
EWEN	1	00	11XXXXXXXX		Enables programming modes.
EWDS	1	00	00XXXXXXXX		Disables all programming modes.
ERASE	1	11	A5–A0		Erases selected register.
WRITE	1	01	A5–A0	D15–D0	Writes data pattern D15-D0 into selected registers.
ERAL	1	00	10XXXXXXXX		Erases all registers.
WRAL	1	00	01XXXXXXXX	D15–D0	Writes data pattern D15-D0 into all registers.

## 2048 by 8-Bit Organization

(NM93C46A when ORG = GND)

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Instruction	SB	OP-Code	Address	Data	Comments
mon dottom	00				Commente
		2 Bits	7 Bits	8 Bits	
READ	1	10	A6-A0		Read data stored in selected registers.
EWEN	1	00	11XXXXXXXXX	XXXX Enables programming modes.	
EWDS	1	00	00XXXXXXXX		Disables all programming modes.
ERASE	1	11	A6-A0		Erases selected register.
WRITE	1	01	A6-A0	D7-D0	Writes data pattern D7-D0 into selected registers.
ERAL	1	00	10XXXXXXXXX		Erases all registers.
WRAL	1	00	01XXXXXXXXX	D7-D0	Writes data pattern D7–D0 into all registers.

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### **Functional Description**

Device	ORG	Memory		
	Pin Logic	Configuration	# of Address Bits	
NM93C46A	0	128 x 8	7 Bits	
	1	64 x 16	6 Bits	

#### Programming:

In all programming modes the READY/BUSY status of the device can be determined by polling the DO pin. After clocking in the last bit of the instruction sequence and with the CS held "high", the DO pin will exit the high impedance state and indicate the READY/BUSY status of the device. DO = logical "0" indicates that programming is still in progress and no other instruction can be executed. DO = logical "1" indicates that the device is READY for another instruction. If CS is forced "low" the DO pin will return to the high impedance state. After the programming cycle has been completed and DO = logical "1", the DO pin can be reset back to the high impedance state by clocking a logical "1" into the DI pin. (This is also performed with the start bit on all op codes, thus clocking an instruction has the same effect.)

#### Read (READ):

The READ instruction outputs serial data on the DO pin. After a READ instruction is received, the instruction and address are decoded, followed by data transfer from the selected memory register into a serial-out shift register. A dummy bit (logical 0) precedes the serial data output string. Output data changes are initiated by a low to high transition of SK after the last address bit (A0) is clocked in.

#### Erase/Write Enable (EWEN):

When  $V_{\rm CC}$  is applied to the part, it "powers up" in the Erase/ Write Disable (EWDS) state. Therefore, all programming modes must be preceded by an Erase/Write Enable (EWEN)

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## Functional Description (Continued)

instruction. Once an Erase/Write Enable instruction is executed, programming remains enabled until an Erase/Write Disable (EWDS) instruction is executed or  $\rm V_{\rm CC}$  is removed from the part.

#### Erase/Write Disable (EWDS):

To protect against accidental data overwrites, the Erase/ Write Disable (EWDS) instruction disables all programming modes and should follow all programming operations. Execution of a READ instruction is independent of both the EVEN and EWDS instructions.

#### Erase (ERASE):

The ERASE instruction will program all bits in the specified register to the logical "1" state. The self-timed programming cycle is initiated on the rising edge of the SK clock as the last address bit (A0) is clocked in. At this point CS, SK, and DI become don't care states. After starting an ERASE cycle the DO pin indicates the READY/BUSY status of the chip if CS is held "high". DO = logical "0" indicates that programming is still in progress. DO = logical "1" indicates that the register, at the address specified in the instruction, has been erased.

### Timing Diagrams for the NM93C46A

#### Write (WRITE):

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The WRITE instruction is followed by 16 bits of data (or 8 bits of data when using the NM93C46A in the x8 organization) to be written into the specified address. The self-timed programming cycle is initiated on the rising edge of the SK clock as the last data bit (D0) is clocked in. At this point, CS, SK and DI become don't care states. No separate ERASE cycle is required before a WRITE instruction.

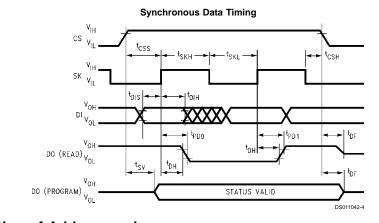
As in the ERASE instruction, after starting a WRITE cycle, the DO pin indicates the READY/BUSY status of the chip if CS is held "high". DO = logical "0" indicates that programming is still in progress. DO = logical "1" indicates that the register, at the address specified in the instruction, has been written and that the part is ready for another instruction.

#### Erase All (ERAL):

The ERAL instruction will simultaneously program all registers in the memory array to the logical "1" state.

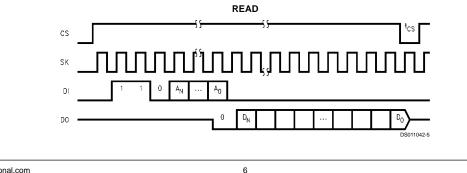
#### Write All (WRAL):

The WRAL instruction will simultaneously program all registers with the data pattern specified in the instruction.

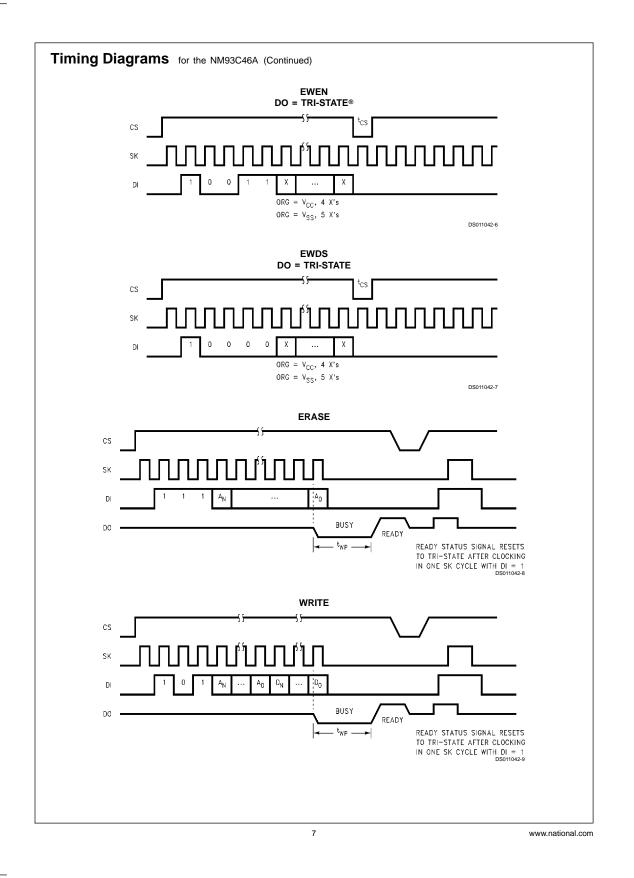


### Organization of Address and Data Fields for NM93C46A

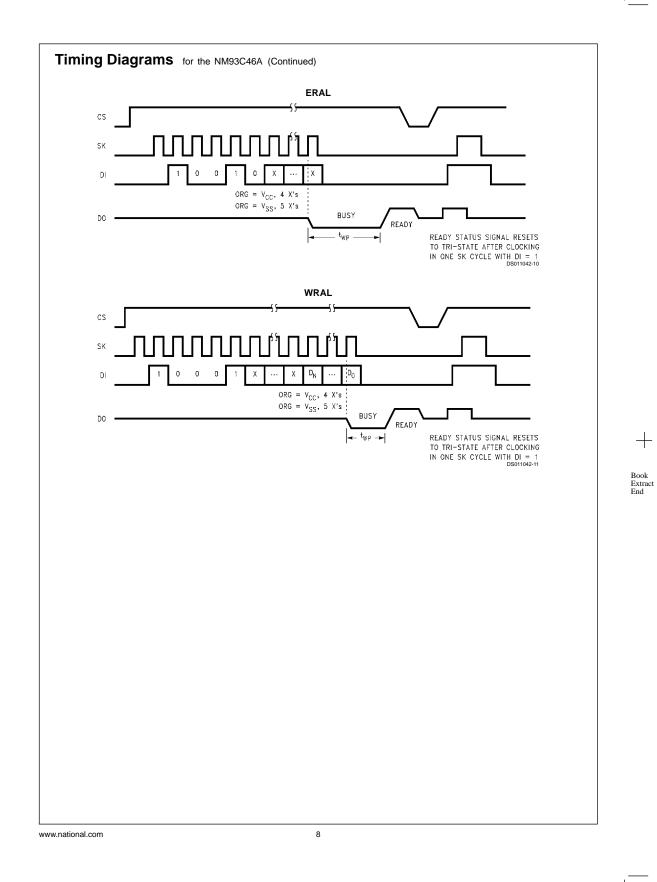
ORG Pin	Organization	A <sub>N</sub>	D <sub>N</sub>	
V <sub>CC</sub> or NC	64 x 16	A5	D15	
V <sub>SS</sub>	128 x 8	A6	D7	



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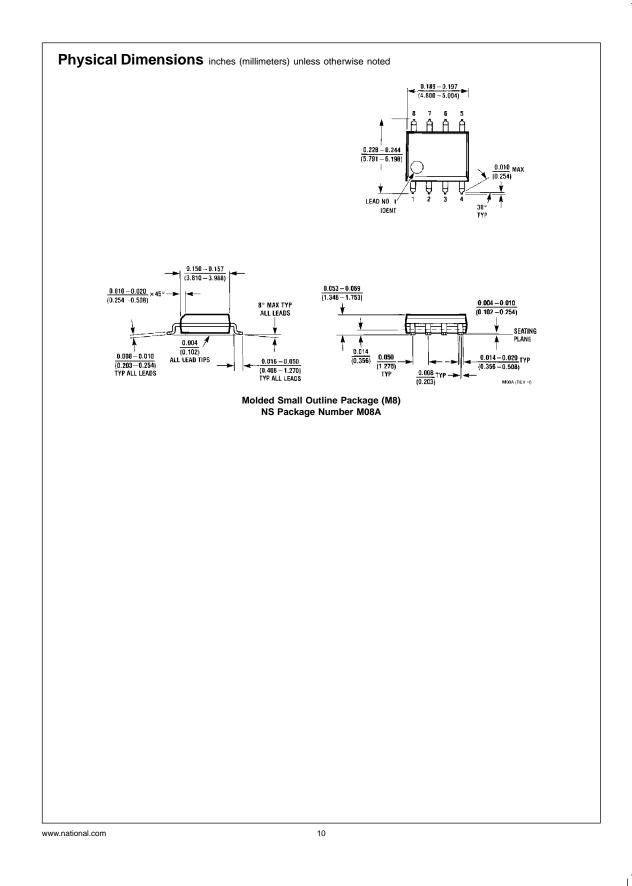
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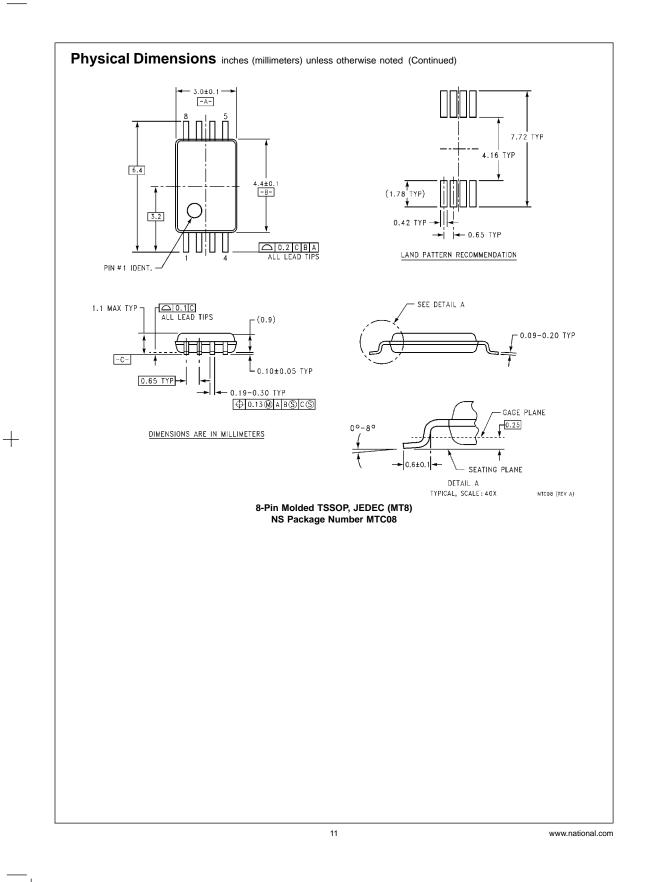
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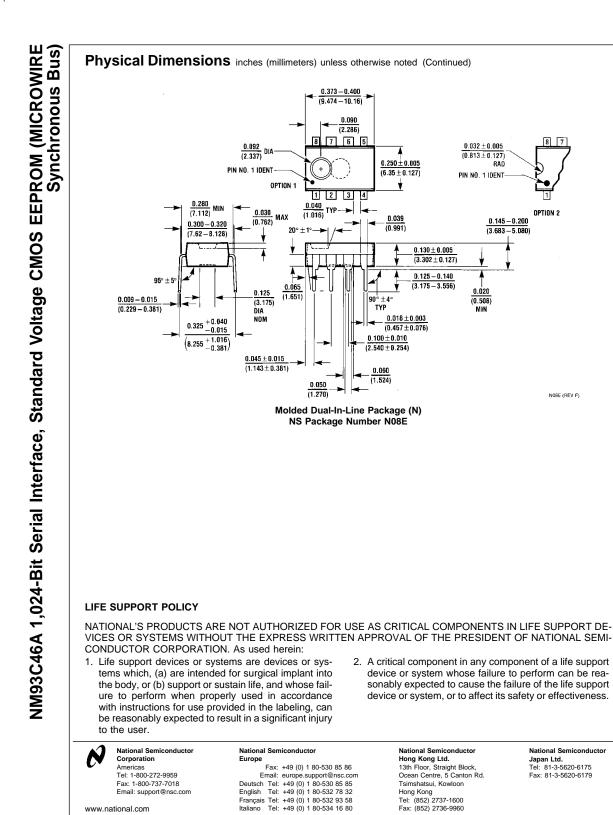
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OPTION 2

NOBE (REV F)

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 $0.032\pm0.005$ 

 $(0.813 \pm 0.127)$ 

PIN NO 1 IDENT

0.020

(0.508) MIN

RAD

0.145-0.200

(3.683-5.080)

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 $0.130 \pm 0.005$  $(3.302 \pm 0.127)$ 

0.125-0.140

(3.175-3.556)

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